

# AGI Safety and Understanding

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# AGI Safety

*“How can we control something that is smarter than ourselves?”*

- Key problems:
  - Value Loading / Value Learning
  - Corrigibility
  - Self-preservation

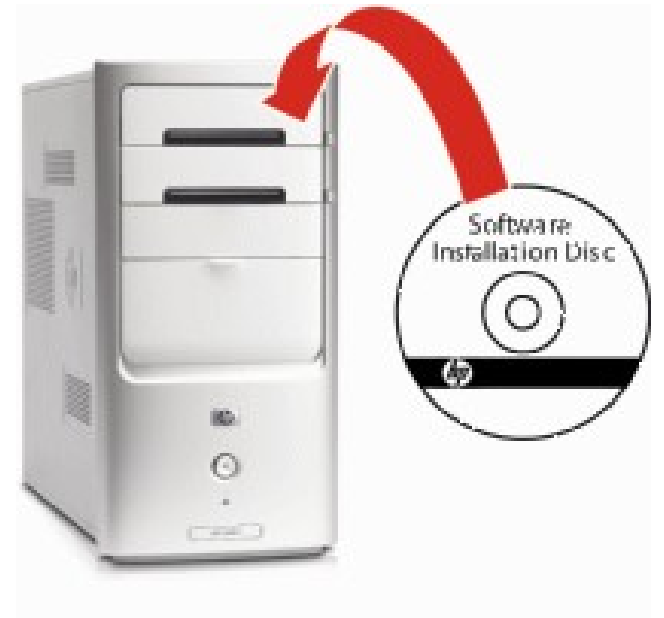
# Value Loading

- Teach AI relevant high level concepts
  - Human
  - Happiness
  - Moral rules

(requires **understanding**)

- Define goal in these terms:

*“Maximise human happiness subject to moral constraints”*



# The Evil Genie Effect

- Goal: Cure Cancer!
- AI-generated plan:
  1. Make lots of money by beating humans at stock market predictions
  2. Solve a few genetic engineering challenges
  3. Synthesize a **supervirus** that wipes out the human species
  4. No more cancer

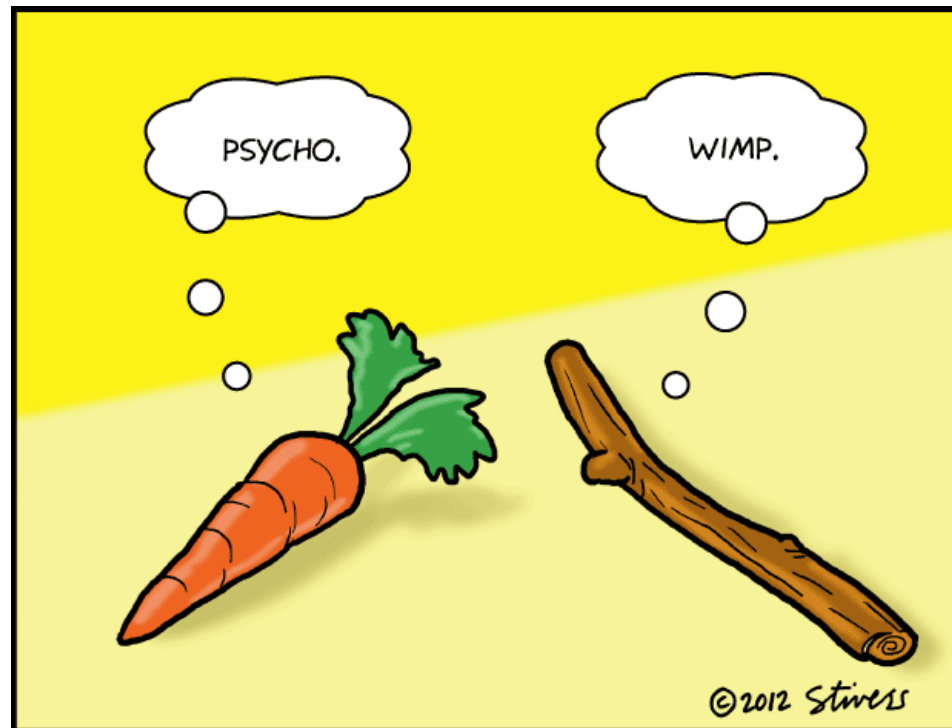
King Midas



<https://anentrepreneurswords.files.wordpress.com/2014/06/king-midas.jpg>

=> Explicit goal specification bad idea

# Value Learning



<http://www.markstivers.com/wordpress/?p=955>

# Reinforcement Learning

(AIXI, Q-learning, ...)



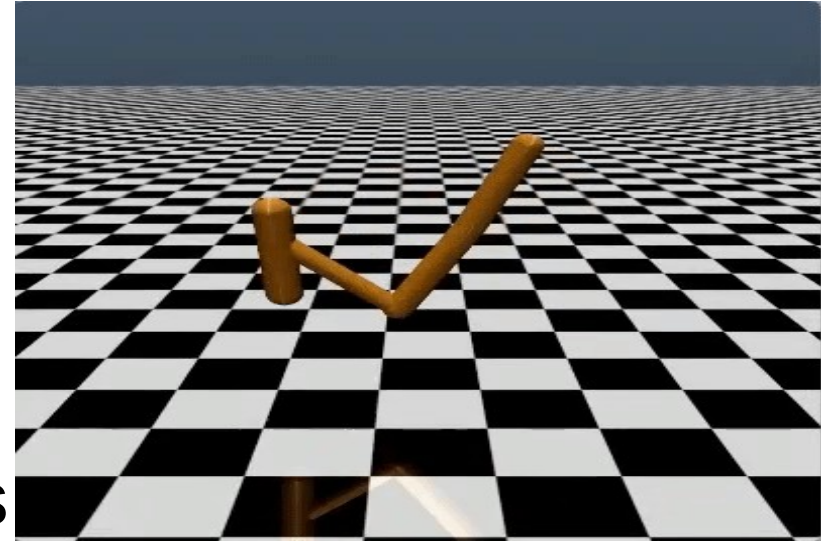
- Requires no **understanding**
- Some problems:
  - Hard to program reward function
  - Laborious to give reward manually
  - Catastrophic exploration
  - Wireheading



# RL Extensions 1:

## Human Preferences

- Learn reward function from human preferences
- Recent OpenAI/Google DeepMind paper
  - Show human short video clips
- **Understanding** required:
  - How communicate scenarios to human? What are the salient features?
  - Which scenarios are possible / plausible / relevant?



# RL Extensions 2

## (Cooperative) Inverse Reinforcement Learning

- Learn reward function from human actions
  - Actions are preference statements
- Helicopter flight  
(Abbeel et al, 2006)
- **Understanding** required:
  - Detect action  
(cf. soccer kick,  
Bitcoin purchase)
  - Infer desire from action





# Limited oversight

- Inverse RL:
  - No oversight required (in theory)
- Learning from Human Preferences:
  - more data-efficient than RL if queries well-chosen



# Catastrophic exploration



- RL:  
“Let’s try!”
- Human Preferences:  
“Hey Human, should I try?”
- Inverse RL:  
“What did the human do?”

# Wireheading

- RL:  
Each state is “self-estimating”  
its reward
- Human Pref. and Inv. RL:  
Wireheaded states can be  
“verified” from outside
- (Everitt et. al., IJCAI-17)



# Corrigibility

- Agent should allow for software corrections and shut down
- Until recently, considered separate problem (Hadfield-Menell et al., 2016; Wangberg et al., **AGI-17**)



*Human pressing shutdown button is a*

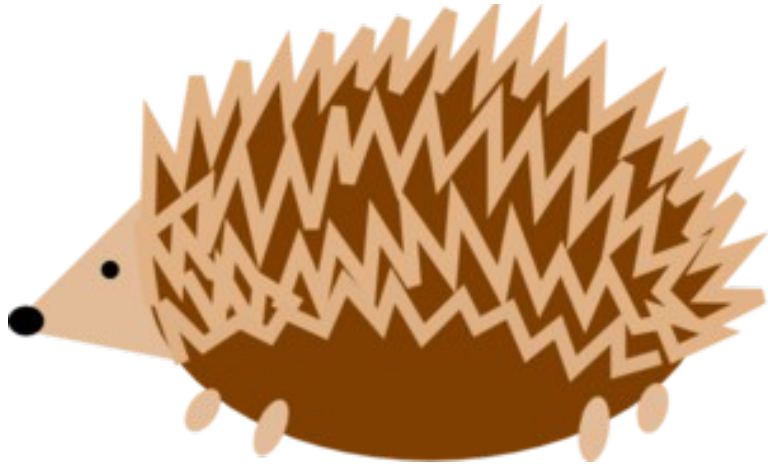
*- strong preference statement/*

*- easily interpretable action*

*that the AI should shut down now*

# Self-Preservation

(of values, corrigibility, software, hardware, ...)



- Everitt et al., AGI-16:  
(some) agents naturally want to self-preserve
- Need **understanding** of self
- Self-understanding?
  - AIXI, Q-learning  
(Off-policy RL)
  - SARSA, Policy Gradient  
(On-policy RL)
  - Cognitive architectures

# Summary

- **Understand**
  - ~~Concepts => specify goals => EVIL GENIE~~
  - Ask and interpret preferences => RL from Human Preferences
  - Identify and and interpret human actions => Inverse RL
  - Self-understanding
- **Properties**
  - Limited oversight
  - Safe(r) exploration
  - Less/no wireheading
  - Corrigibility
  - Self-preservation

# References

- Deep Reinforcement Learning from Human Preferences. *Christiano et al.*, NIPS 2017.
- Reinforcement Learning from a Corrupted Reward Channel. *Everitt et al.* IJCAI, 2017.
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- The Off-Switch Game. *Hadfield-Menell et al.* Arxiv, 2016.
- A Game-Theoretic Analysis of the Off-Switch Game. *Wangberg et al.*, AGI 2017.
- Self-Modification of Policy and Utility Function in Rational Agents. *Everitt et al.*, AGI 2016.
- Superintelligence: Paths, Dangers, Strategies. *Bostrom*, 2014.
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